

EXTREMAL SOLUTIONS TO SOME ART GALLERY AND TERMINAL-PAIRABILITY PROBLEMS

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PhD defense,

17 November 2017, Budapest

Art gallery problems

Terminal-pairability problem

abstract models of challenges that appear in the world

geometric algorithms

edge-connectivity, network flow

image processing, VLSI design

routing traffic in networks

NP-hard, unknown to be polynomial time, or $O(n^{17})$

1. **Group** the instances of the problem by the value of a “meaningful” parameter

THE METAMETHOD: THE EXTREMAL-TYPE APPROACH

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2. In each group, **find** (up to a constant) sharp **bounds** on the optimal solution of the **worst case** in the group

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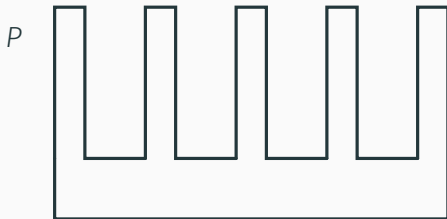
THE METAMETHOD: THE EXTREMAL-TYPE APPROACH

1. **Group** the instances of the problem by the value of a “meaningful” parameter
2. In each group, **find** (up to a constant) sharp **bounds** on the optimal solution of the **worst case** in the group
3. For an instance of the problem in the group, a solution achieving the above bound is usually a **good approximation** of the optimum
4. Moreover, such a solution can often be **constructed efficiently** (in polynomial time)

RESULTS IN ART GALLERY PROBLEMS

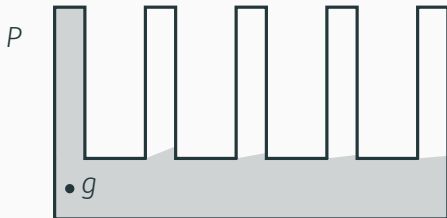
THE ART GALLERY PROBLEM (IN ORTHOGONAL POLYGONS)

- Art gallery: $P \subset \mathbb{R}^2$, a simple orthogonal polygon



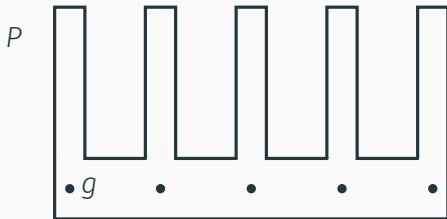
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THE ART GALLERY PROBLEM (IN ORTHOGONAL POLYGONS)

- Art gallery: $P \subset \mathbb{R}^2$, a simple orthogonal polygon
- Point guard: fixed point $g \in P$, has 360° line of sight vision
- Objective: place guards in the gallery so that any point in P is seen by at least one of the guards



Give (if possible, sharp) bounds on the number of guards required to control the gallery as a function of the number of its vertices.

Theorem (Kahn, Klawe and Kleitman, 1980)

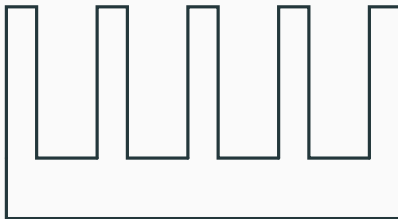
$\lfloor \frac{n}{4} \rfloor$ guards are sometimes necessary and always sufficient to cover the interior of a simple orthogonal polygon of n vertices.

Proof: via convex quadrilateralization.

THE ART GALLERY THEOREM FOR ORTHOGONAL POLYGONS

Theorem (Györi and O'Rourke independently, around 1984)

Every orthogonal polygon of n vertices can be partitioned into $\lfloor \frac{n}{4} \rfloor$ orthogonal polygons of at most 6 vertices.



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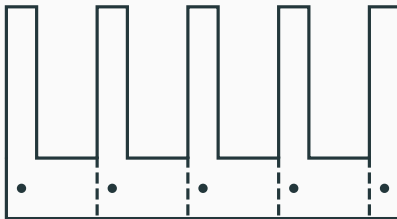
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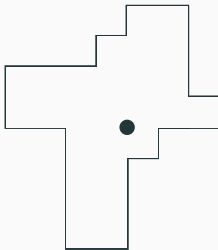
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PARTITIONING ORTHOGONAL POLYGONS

Theorem (Hoffmann, 1990)

Any n -vertex orthogonal polygon with holes can be partitioned into at most $\lfloor \frac{n}{4} \rfloor$ at most 16-vertex simple orthogonal star pieces.



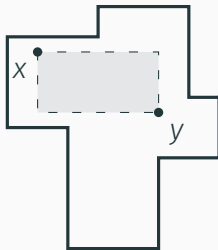
A 16-vertex orthogonal star.

Metatheorem

Every (orthogonal) art gallery theorem has an underlying partition theorem.

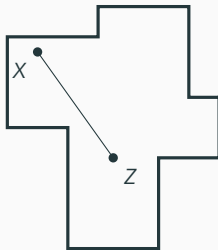
RECTANGULAR VISION

Rectangular vision: two points $x, y \in P$ have r -vision of each other if there is an axis-parallel rectangle inside P , containing x and y .



RECTANGULAR VISION

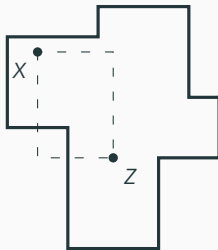
Rectangular vision: two points $x, y \in P$ have r -vision of each other if there is an axis-parallel rectangle inside P , containing x and y .



x and z have unrestricted vision of each other

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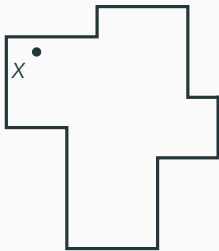
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x and z do not have rectangular vision of each other

RECTANGULAR VISION

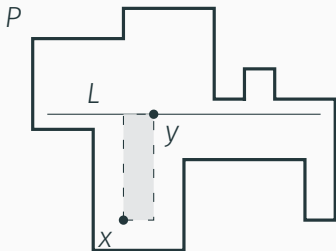
Rectangular vision: two points $x, y \in P$ have r -vision of each other if there is an axis-parallel rectangle inside P , containing x and y .



The extremal bound is the same with rectangular vision

MOBILE GUARDS IN ORTHOGONAL POLYGONS

A mobile guard is an axis-parallel line segment $L \subset P$ inside the art gallery. The guard sees a point $x \in P$ iff there is a point $y \in L$ such that x is visible from y .



This orthogonal polygon can be covered by one mobile guard

Theorem (Aggarwal, 1984)

$\lfloor \frac{3n+4}{16} \rfloor$ mobile guards are sometimes necessary and always sufficient to cover the interior of a simple orthogonal polygon of n vertices.

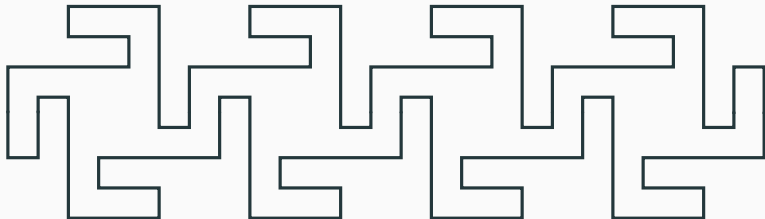
Two questions of O'Rourke (1987):

- Can crossing patrols be avoided?
- Is it enough that the guards have visibility at the two endpoints of their patrols?

PARTITIONING ORTHOGONAL POLYGONS

Theorem (Györi, M, 2016)

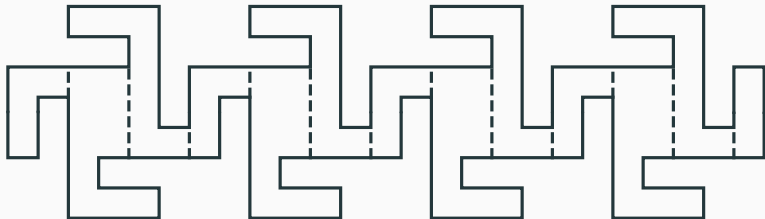
Any n -vertex simple orthogonal polygon can be partitioned into at most $\lfloor \frac{3n+4}{16} \rfloor$ at most 8-vertex pieces.



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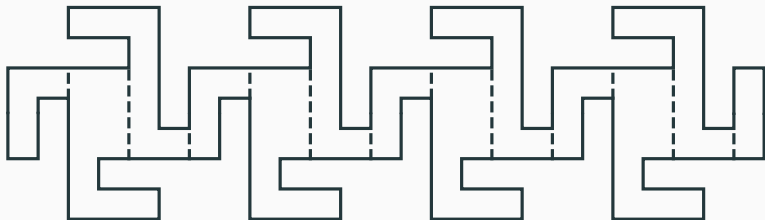
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Any at most 8-vertex orthogonal polygon can be covered by one mobile guard!

- The complexity of the minimum size mobile guard system is unknown, probably NP-hard.
- The previous partitioning theorem can be turned into a linear time algorithm.

COMPARING POINT GUARDS TO MOBILE GUARDS

	Point guard	Mobile guard
General polygons	$\lfloor \frac{n}{3} \rfloor$	$\lfloor \frac{n}{4} \rfloor$
Orthogonal polygons	$\lfloor \frac{n}{4} \rfloor$	$\lfloor \frac{3n+4}{16} \rfloor$

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$\frac{3}{4}$
→

IS THIS 3 : 4 RATIO ONLY AN EXTREMAL
PHENOMENON?

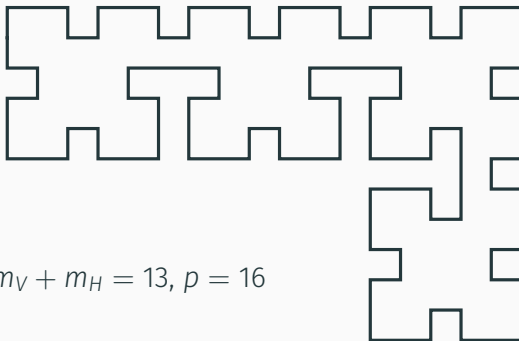
- p : minimum number of point guards required to control P
- m_V : minimum number of mobile guards, whose patrol is a **vertical** line segment, required to control P
- m_H : minimum number of mobile guards, whose patrol is a **horizontal** line segment, required to control P

Theorem (Györi, M, 2016)

For any simple orthogonal polygon

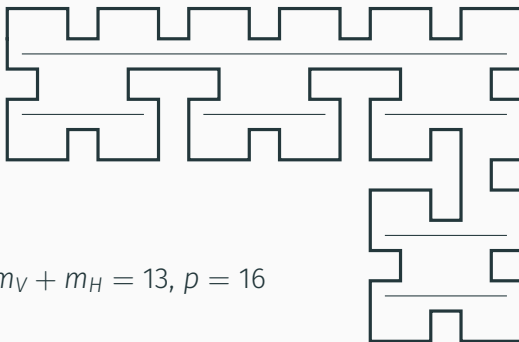
$$\frac{m_V + m_H - 1}{p} \geq \frac{3}{4},$$

and this result is sharp.



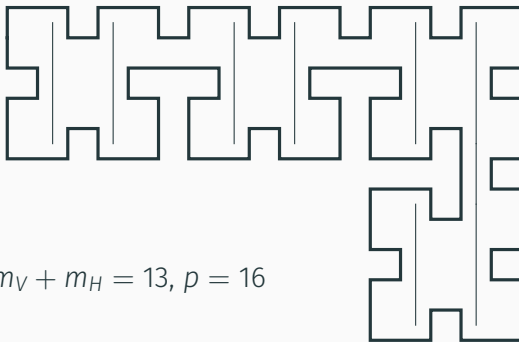
A new block requires 4 more point guards, but only 3 more vertical + horizontal mobile guards.

SHARPNESS



$$m_V + m_H = 13, p = 16$$

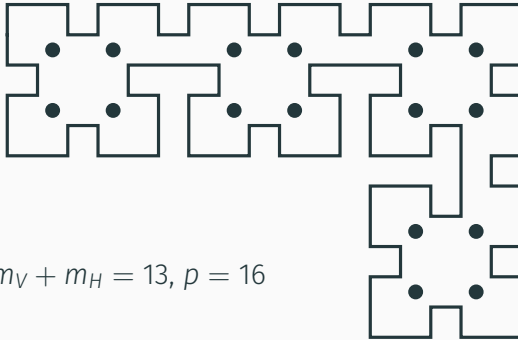
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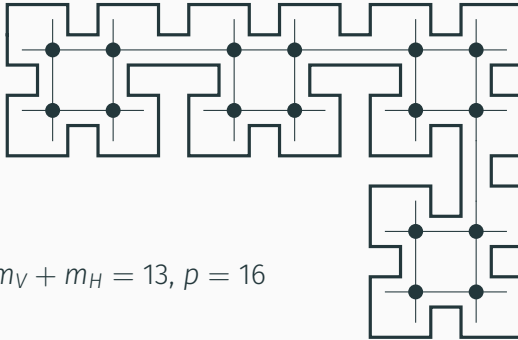
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The minimum size horizontal mobile guard system can be computed in linear time.

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Corollary

An $\frac{8}{3}$ -approximation of the minimum size of a point guard system of an orthogonal polygon can be computed in linear time.

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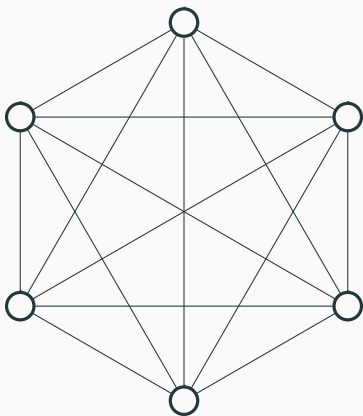
Corollary

An $\frac{8}{3}$ -approximation of the minimum size of a point guard system of an orthogonal polygon can be computed in linear time.

Optimal point guard problem: generally NP-hard. However, Worman and Keil (2007) showed that it can be computed in $\tilde{O}(n^{17})$ for orthogonal polygons and rectangular vision.

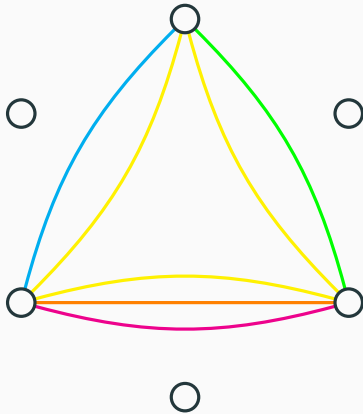
RESULTS IN TERMINAL-PAIRABILITY

EDGE-DISJOINT PATHS PROBLEM



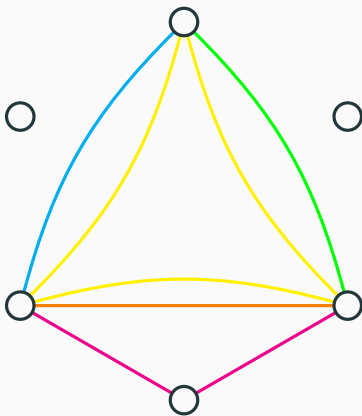
Base graph

EDGE-DISJOINT PATHS PROBLEM



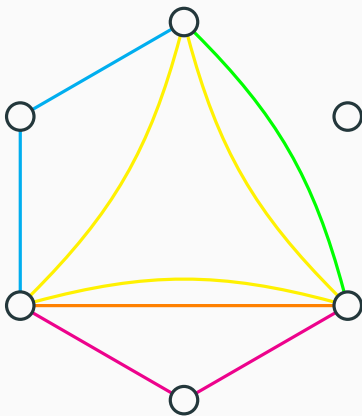
Demand graph

EDGE-DISJOINT PATHS PROBLEM



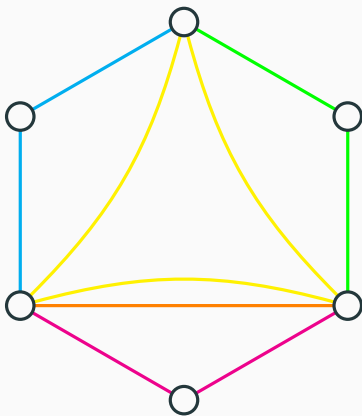
Resolving multiplicities

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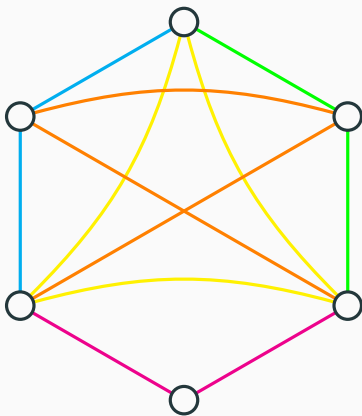
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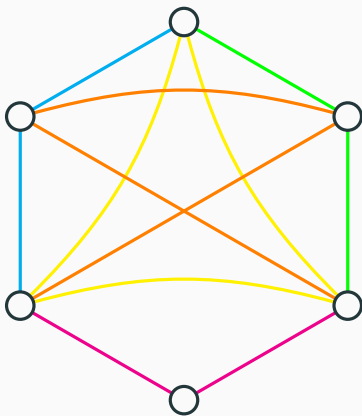
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EDGE-DISJOINT PATHS PROBLEM



Solution/Realization

EDGE-DISJOINT PATHS PROBLEM



EDP is NP-hard (Karp, 1972), even for complete base graphs

THE TERMINAL-PAIRABILITY PROBLEM

- Solving every instance of the edge-disjoint paths problem separately is hopeless
- Let's test a single base graph against a set of demand graphs characterized by a degree restriction.
- Motivation: given network switches with a fixed number of ports, build larger switches from them as components

Problem (Csaba, Ralph J. Faudree, András Gyárfás, Jenő Lehel, and Schelp, 1992)

What is the highest number q for which any demand graph on n vertices and maximum degree q is realizable in K_n ?

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Theorem (Csaba, Ralph J. Faudree, András Gyárfás, Jenő Lehel, and Schelp, 1992)

$$\frac{n}{7.5} \leq q \leq \frac{n}{2}.$$

Theorem (Győri, M, Mészáros, 2016)

Any demand graph D on n -vertices with $\Delta(D) \leq 2\lfloor \frac{n}{6} \rfloor - 4$ is realizable in K_n .

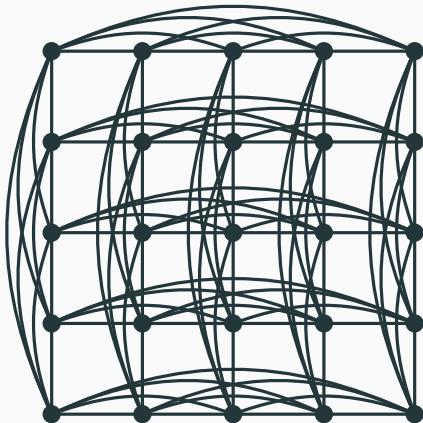
Theorem (Kosowski, 2008)

Let D be a demand graph on the vertex set of K_n . There is an $O(mn \log n)$ time algorithm which gives a 3.75-approximation solution to the MAXEDP problem in K_n .

Theorem (M, 2017)

Let D be a demand graph on the vertex set of K_n . There is an $O(mn \log n + n^3)$ time algorithm which gives a $(3 + O(1/n))$ -approximation solution to the MAXEDP problem in K_n .

COMPLETE GRID GRAPH, $d = 2$



$$K_5 \square K_5 = K_5^2$$

Theorem (Györi, M, Mészáros, 2016)

Let $G = K_t^d$ and let $D = (V(D), E(D))$ be a demand graph with $V(D) = V(K_t^d)$ and $\Delta(D) \leq 2 \lfloor \frac{t}{12} \rfloor - 2$. Then D can be realized in G .

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G is **path-pairable**, if any matching of its vertices can be realized in G .

Corollary

If $t \geq 24$, K_t^d is path-pairable.

Suppose any matching can be realized in G and $\Delta(G) \leq \Delta$.
What is the maximum of $N = |V(G)|$?

Theorem (Ralph J. Faudree, András Gyárfás, and Jenő Lehel, 1999)

$$N \leq 2\Delta^\Delta.$$

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$$\Delta^2 \leq N$$

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$$24^{\Delta/23} \leq N \leq 2\Delta^\Delta.$$

THANK YOU FOR YOUR ATTENTION!

-  Ervin Győri, Tamás Róbert Mezei, (2016). “Partitioning orthogonal polygons into ≤ 8 -vertex pieces, with application to an art gallery theorem”. In: *Comput. Geom.* 59, pp. 13–25.
-  Ervin Győri, Tamás Róbert Mezei, Gábor Mészáros, (2016). “Terminal-Pairability in Complete Graphs”. In: *J. Combin. Math. Combin. Comput.* Accepted for publication.
-  Lucas Colucci, Péter L Erdős, Ervin Győri, Tamás Róbert Mezei, (2017a). “Terminal-Pairability in Complete Bipartite Graphs”. In: *Discrete Appl. Math.* Accepted for publication.





Dóra Dedinszki, Flóra Szeri, Eszter Kozák, Viola Pomozi, Natália Tőkési, Tamás Róbert Mezei, Kinga Merczel, Emmanuel Letavernier, Ellie Tang, Olivier Le Saux, Tamás Arányi, Koen Wetering, András Váradi, (2017). “Oral administration of pyrophosphate inhibits connective tissue calcification”. In: *EMBO Molecular Medicine* 9.11, pp. 1463–1470.



Ervin Győri, Tamás Róbert Mezei, Gábor Mészáros, (2017). “Note on terminal-pairability in complete grid graphs”. In: *Discrete Math.* 340.5, pp. 988–990.

SUBMITTED PUBLICATIONS

-  Lucas Colucci, Péter L Erdős, Ervin Győri, Tamás Róbert Mezei, (2017b). “Terminal-Pairability in Complete Bipartite Graphs with Non-Bipartite Demands”. In: *submitted to Theoret. Comput. Sci.*
-  Ervin Győri, Tamás Róbert Mezei, (2017). “Mobile vs. point guards”. In: *submitted to Discrete Comput. Geom.*

I AM VERY GRATEFUL TO...

- My supervisor, *Ervin* (who in any situation has a relevant story about a well-known mathematician),
- *Gábor Mészáros*, coauthor of the papers about terminal-pairability,
- My parents,
- My partner, *Eszter*,
- My alma mater, *CEU*

for their continuous support during my studies and the writing of my thesis.